

# the Spaceborne Wind Lidar Mission



# ADM-Aeolus Industrial Consortium



Overall Prime Contractor:	EADS-Astrium (UK)
Aeolus Satellite:	EADS-Astrium (Germany)
ALADIN Instrument Prime:	EADS-Astrium (France)
Transmitter Laser Prime:	Galileo Avionica (Italy)
with subs Amplifiers:	Quantel (France)
Laser Diode Stacks:	Thales Laser Diodes (France)
Reference Laser:	TESAT (Germany)
Master Oscillator/Harmonics:	CESI (Italy)
ALADIN Optics:	Kaiser-Threde (Germany)
Receiver Interferometers:	Contraves (CH)
Accumulation CCDs:	e2v (UK)
Detection Front End Unit:	SIRA (UK)
Detection Electronics:	Patria (Finland)
plus about 20 other companies from ESA countries for various other instrument and satellite subsystems	



# ADM-Aeolus Mission Overview



The need for global measurements of wind profiles is well established.

ESA has been studying Wind Lidar technology since the eighties, and started a full Phase A mission study in 1998.

The Atmospheric Dynamics Mission was selected in Oct 1999 as second core mission of the Earth Explorer Program.

Predevelopment (instrument refinement, transmitter laser, laser diode stacks) started in 2000, and mission Phase B began July 2002, and Phase C/D Oct 2003. Launch planned for end 2008.

The Atmospheric Dynamics Mission ADM-Aeolus will demonstrate the feasibility of spaceborne wind lidars for global wind profiling and is a precursor for an operational wind profiler system.



## Keep it simple: Single Line-of-Sight wind profiles



- A study to define best scan strategy (Lorenc, 1992) resulted in understanding that improvement of Numerical Weather Prediction is nearly independent on direction of wind components measured, i.e. same improvement for two single direction vectors as for one 2-D vector (mainly the number of boundary conditions for NWP models counts)
  - The measurement of a single component (LOS) wind profiles simplifies wind lidar instrument design significantly:
    - No scanner required
    - No lag-angle compensation
    - Pointing orthogonal to ground velocity: no wind speed-offset due to satellite velocity
    - Pointing to night side of orbit to reduce background

# Aeolus System Requirements



<b>Vertical resolution: 0.5 km to 2 km 1 km to 16 km 2 km to 30 km (total up to 25 layers)</b>	<b>Requires Mie and Rayleigh channel to measure over full altitude range</b>
<b>Horizontal average wind over 50 km  Profile spacing 200 km to fit NWP needs</b>	<b>7 s averaging  28 s per observation</b>
<b>Global coverage (200 profiles per orbit) for three years in orbit</b>	<b>Drives lifetime qualification</b>
<b>LOS wind accuracy: 1 m/s up to 2 km 2 m/s up to 16 km</b>	<b>Drives sizing of lidar</b>
<b>Bias: less than 0.4 m/s offset  Linearity: less than 0.7 %* actual speed</b>	<b>Drives stability of lidar calibration</b>
<b>Dynamic range: -150 to +150 m/s</b>	

# Consequences of the Aeolus System Requirements

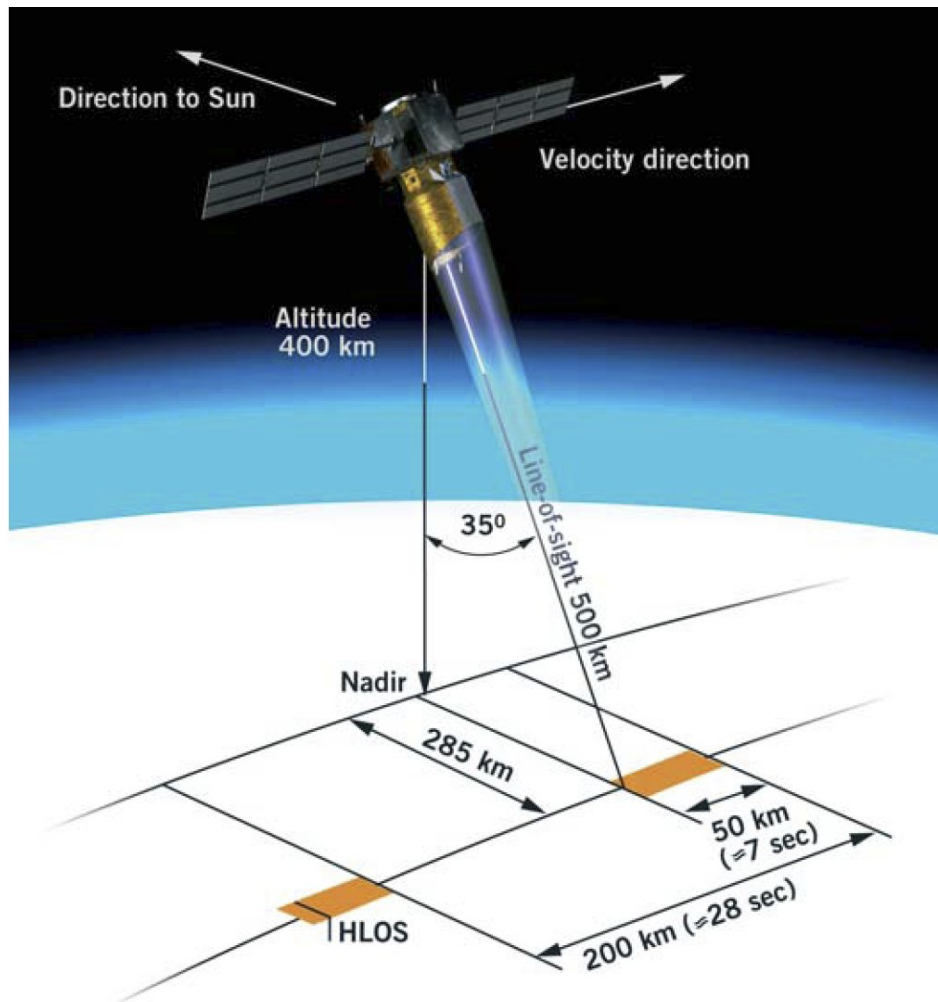


Trades were performed between potential lidar systems to meet the system requirements. Key contenders were

- Coherent 2  $\mu\text{m}$  solid-state laser system, and
- Incoherent 355 nm solid-state laser system.

Requirement to measure high altitude winds was the key driver for decision for 355 nm incoherent system. High altitude wind patterns are considered key parameters for weather forecasts (in particular lower stratospheric winds), thus Rayleigh scattering is essential for these measurements, i.e. incoherent UV system.

# Aeolus Implementation



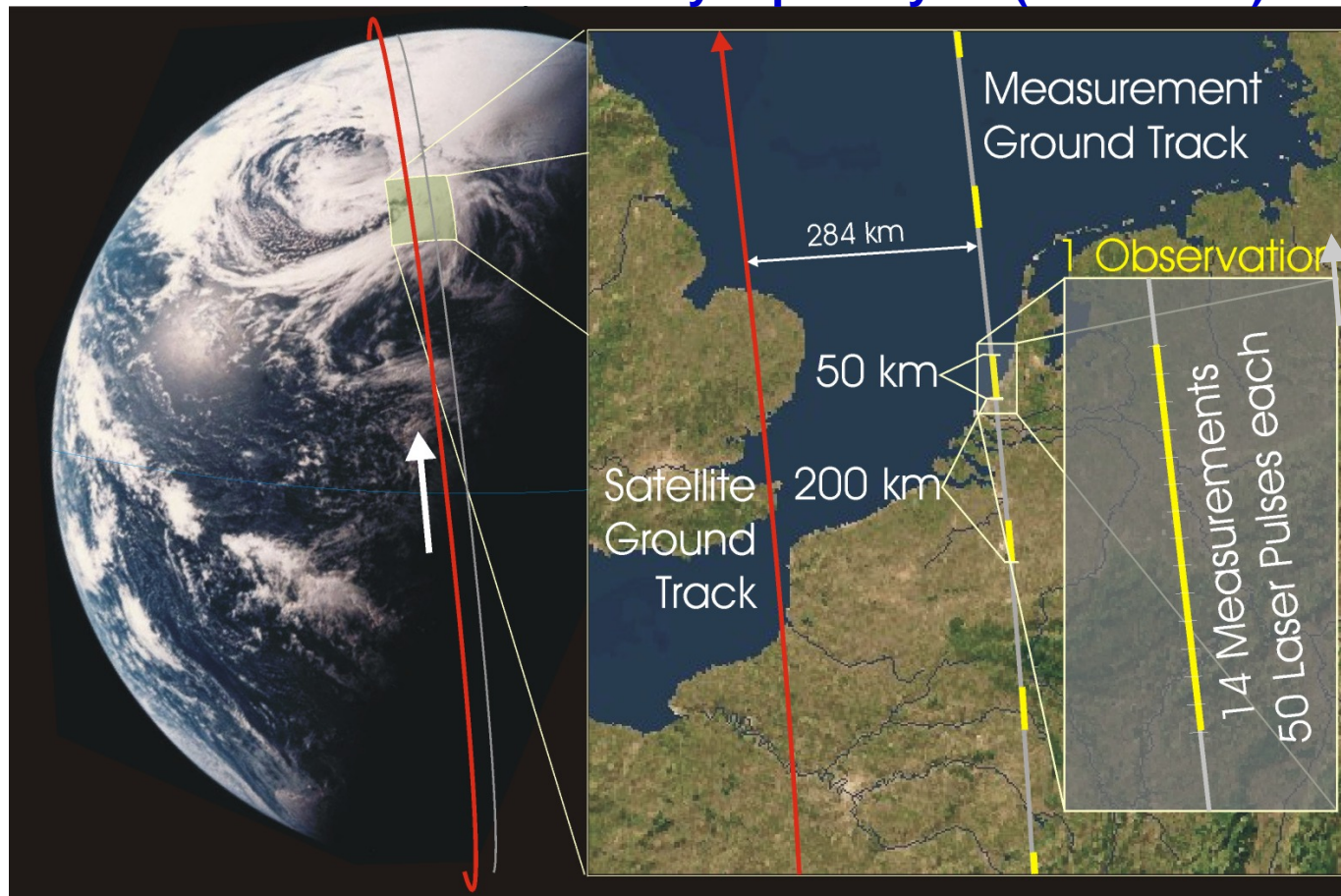
## Baseline Technology:

- Direct detection UV lidar (355 nm) with two receivers:
- Mie receiver to determine winds from aerosol backscatter
- Rayleigh receiver to obtain wind information from molecular backscatter of a clear atmosphere
- Mie and Rayleigh receivers can sample the atmosphere with different altitude steps
- The line-of-sight is pointing 35 deg from nadir orthogonal to the ground track velocity vector to minimize the Doppler shift from the 7 km/s satellite velocity

# Aeolus Orbit and Measurement Track



Aeolus is in a dusk-dawn sun-synchronous orbit of about 400 km altitude with a 7-day repeat cycle (109 orbits).

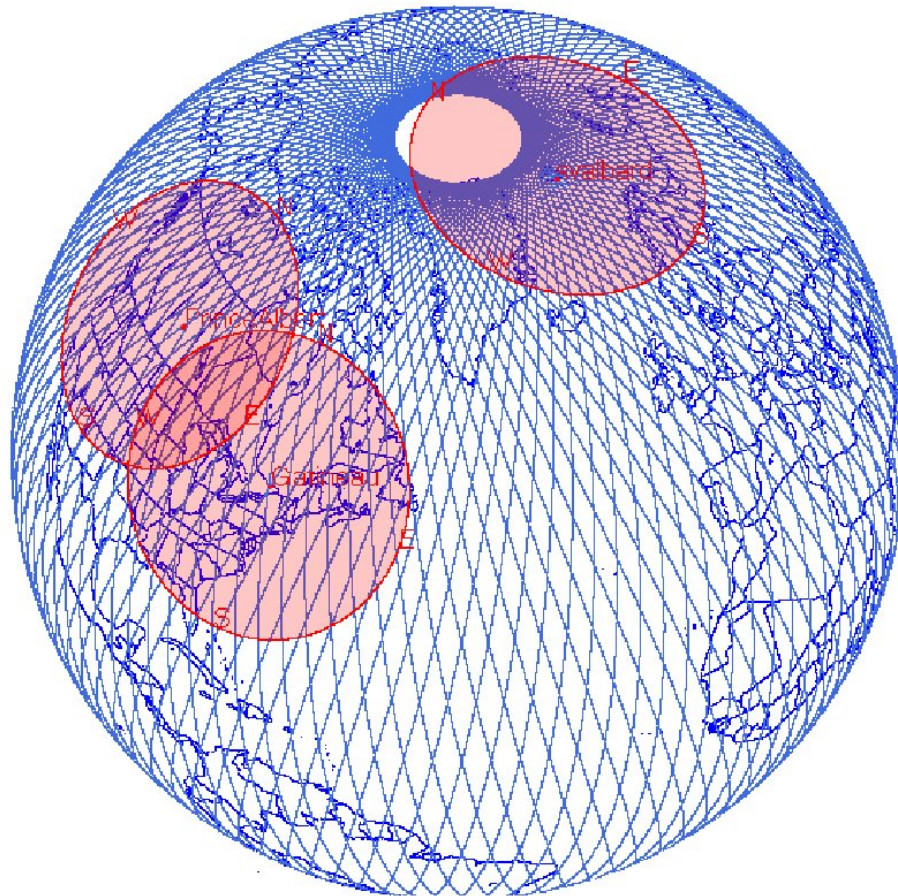


Aeolus measures HLOS-wind profiles averaged over 50 km observations (corresponding 7 s flight time).

The observations are 200 km apart (corresponding 28 s flight time).

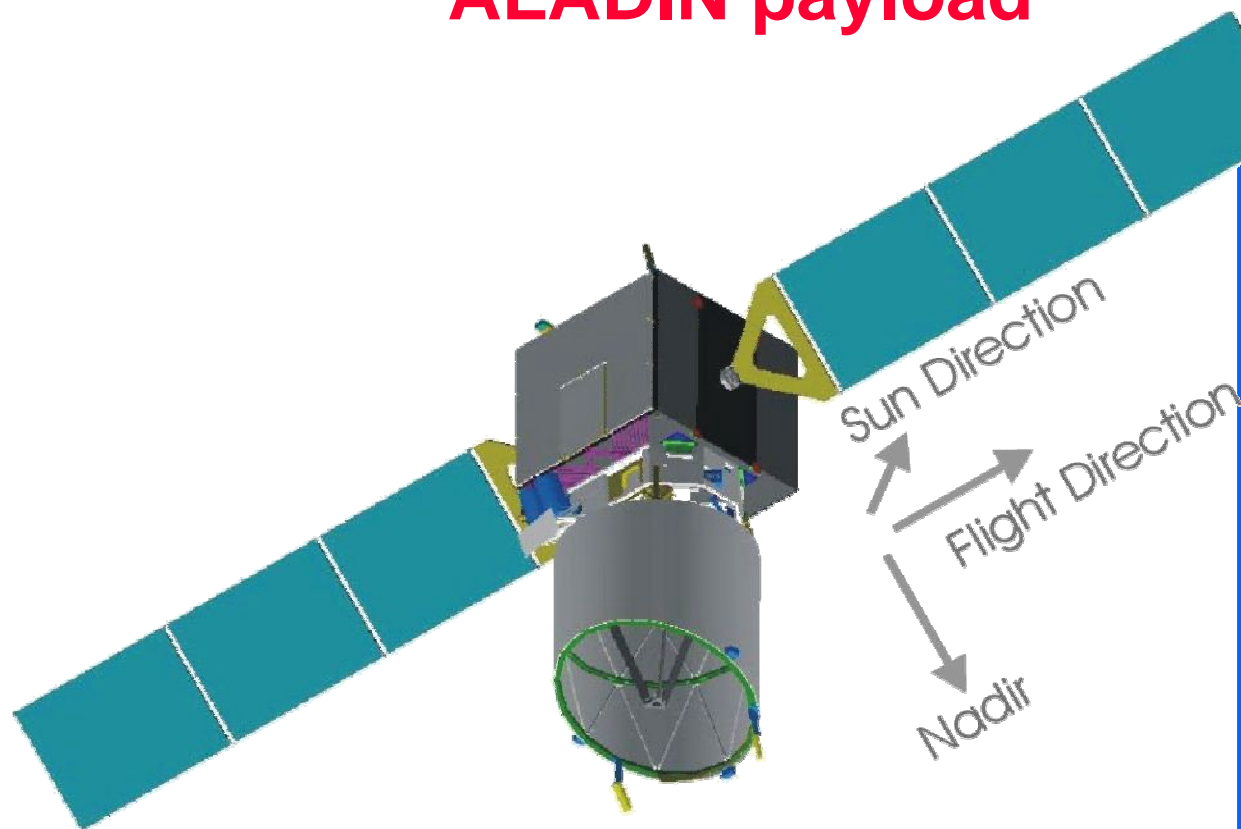
Picture shows the measurement track over 150 s duration.

# Data Receiving Station Svalbard



**Single data reception station in Svalbard allows downlink every orbit; Aeolus allows addition of fill-in stations to reduce data latency to 30 min for regional data.**

## Aeolus satellite with its ALADIN payload

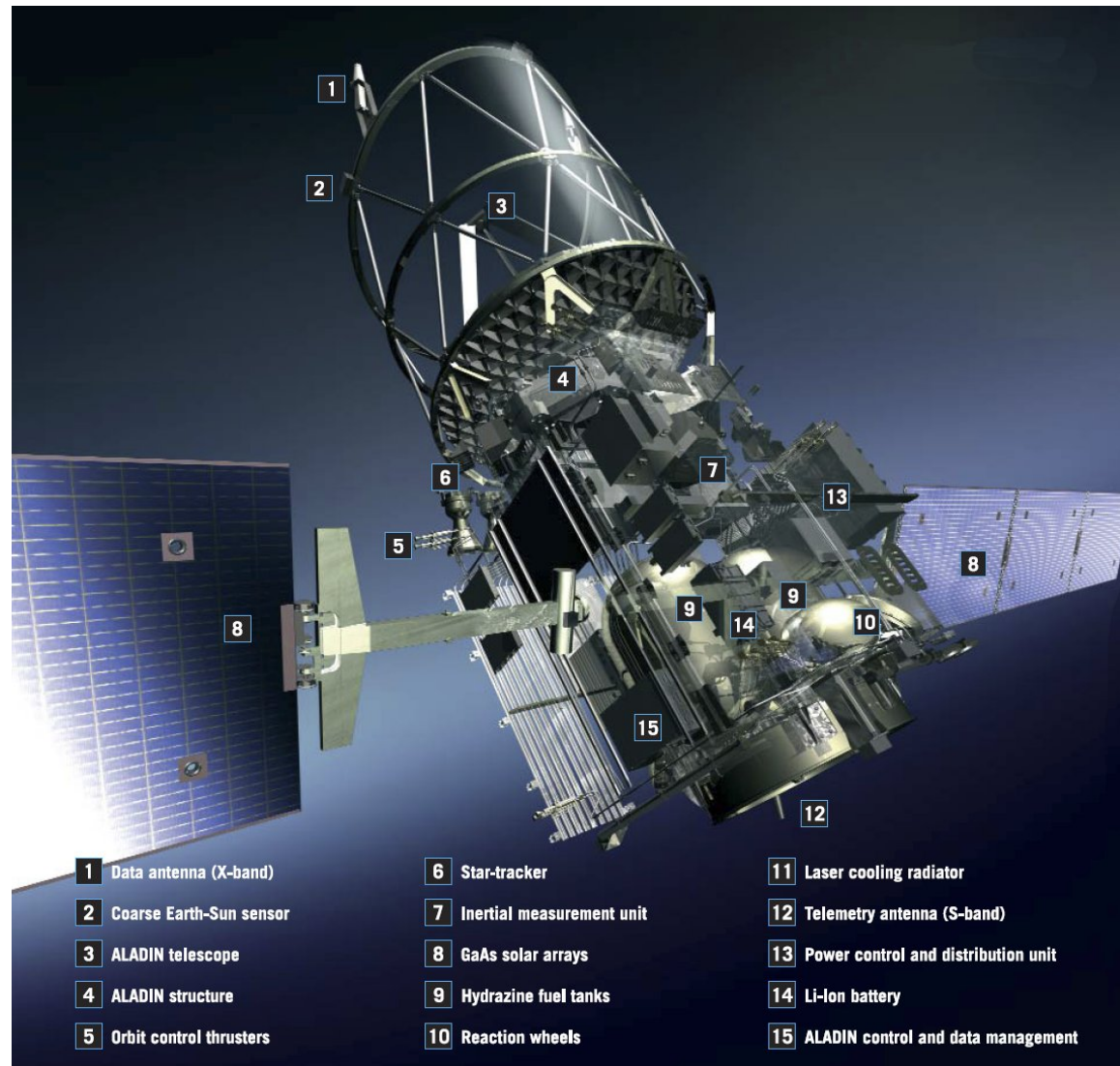


Aeolus mass is 1.1 t (plus fuel), the solar arrays are about 13 m wide to produce 2.2 kW (orbital average power 1.4 kW). It is compatible with small launchers (Rockot, Dneper, Vega).

It carries a single payload, the Atmospheric LAser Doppler INstrument ALADIN.

The satellite is designed for simple operation (7 day autonomy, 5 day unattended survival), repeating 7-day command cycles.

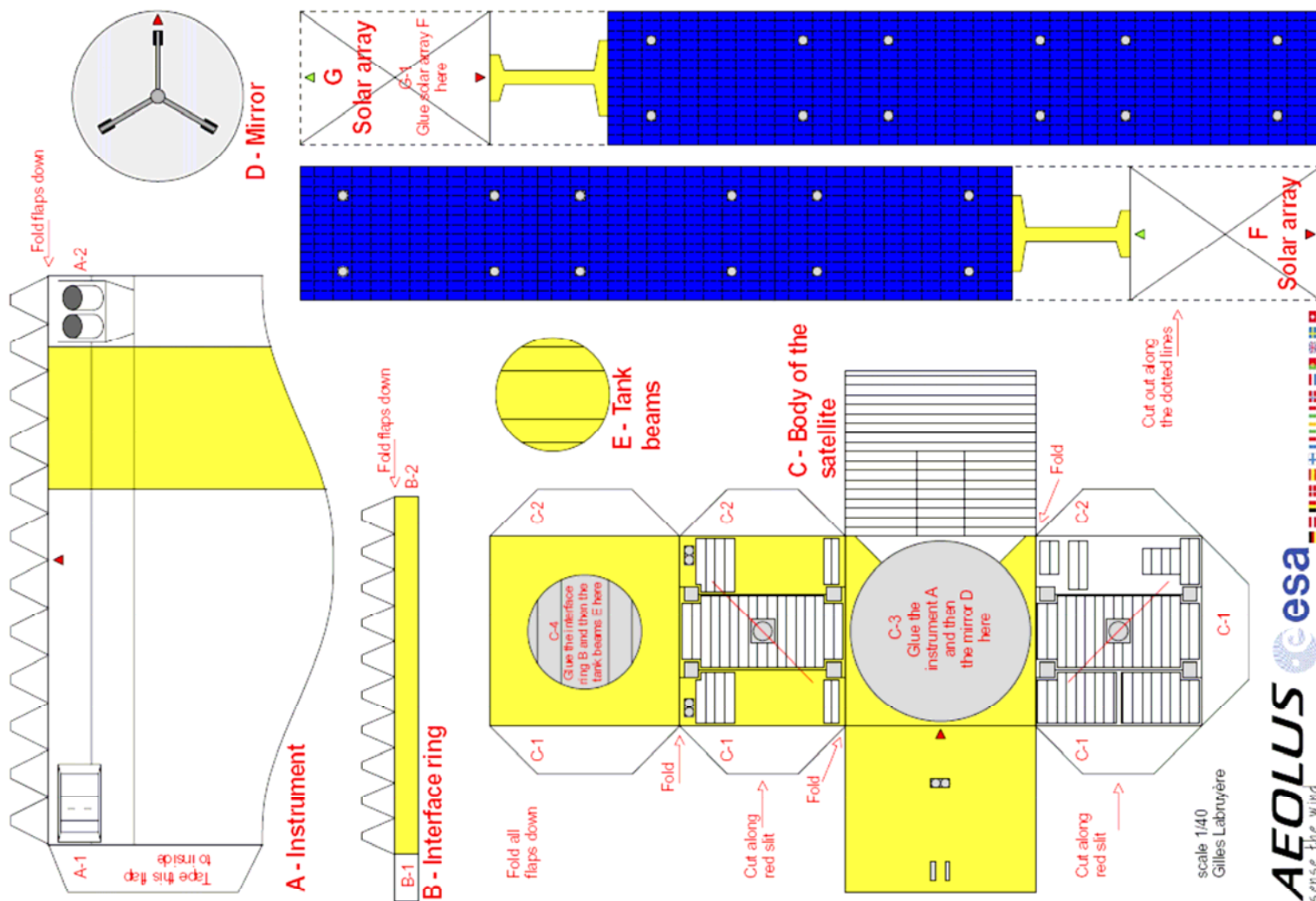
# Aeolus satellite



Artist's view  
showing the  
location of most  
satellite and  
ALADIN  
subsystems

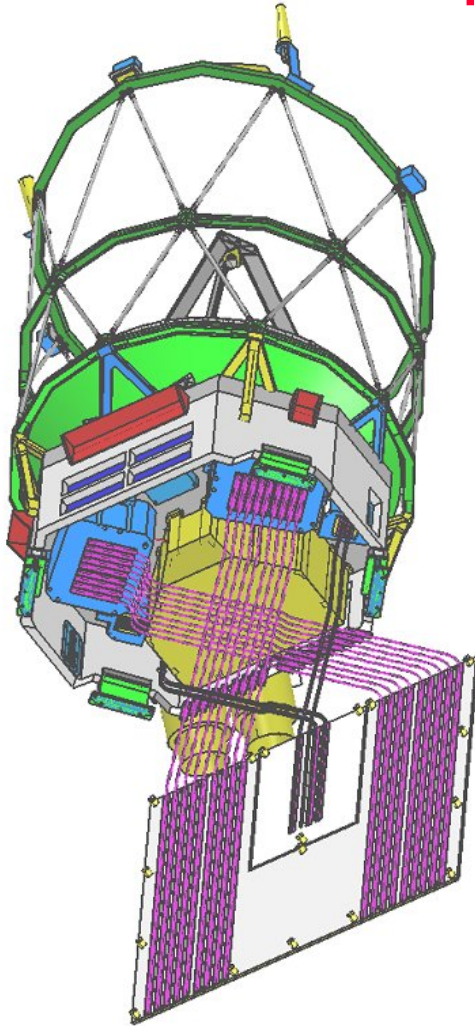


# Build your own Aeolus



# ALADIN

## Atmospheric Laser Doppler Instrument



ALADIN is the only payload of Aeolus. Its size is dominated by the large afocal telescope of 1.5 m diameter.

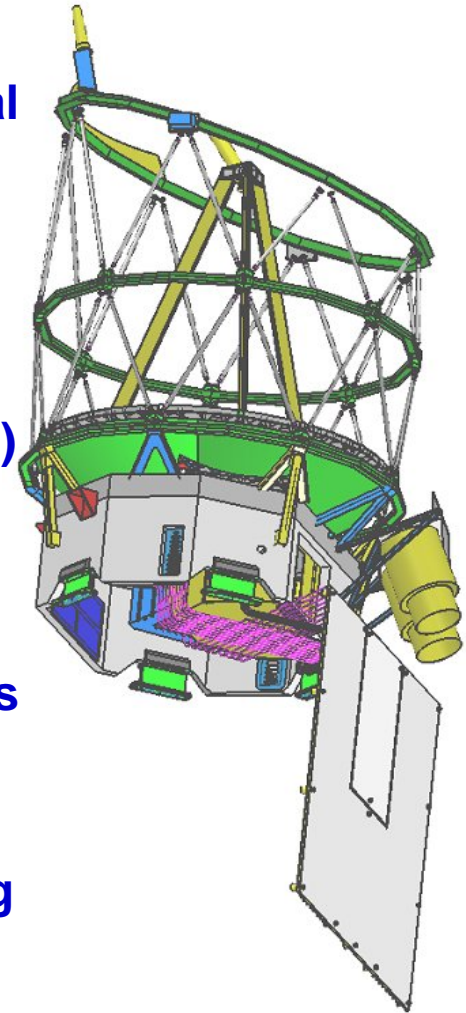
It uses diode pumped Nd:YAG laser to generate UV-light pulses (355 nm) emitted to the atmosphere.

Two transmitter laser assemblies (blue) and the receiver (yellow) are on the structure below the telescope.

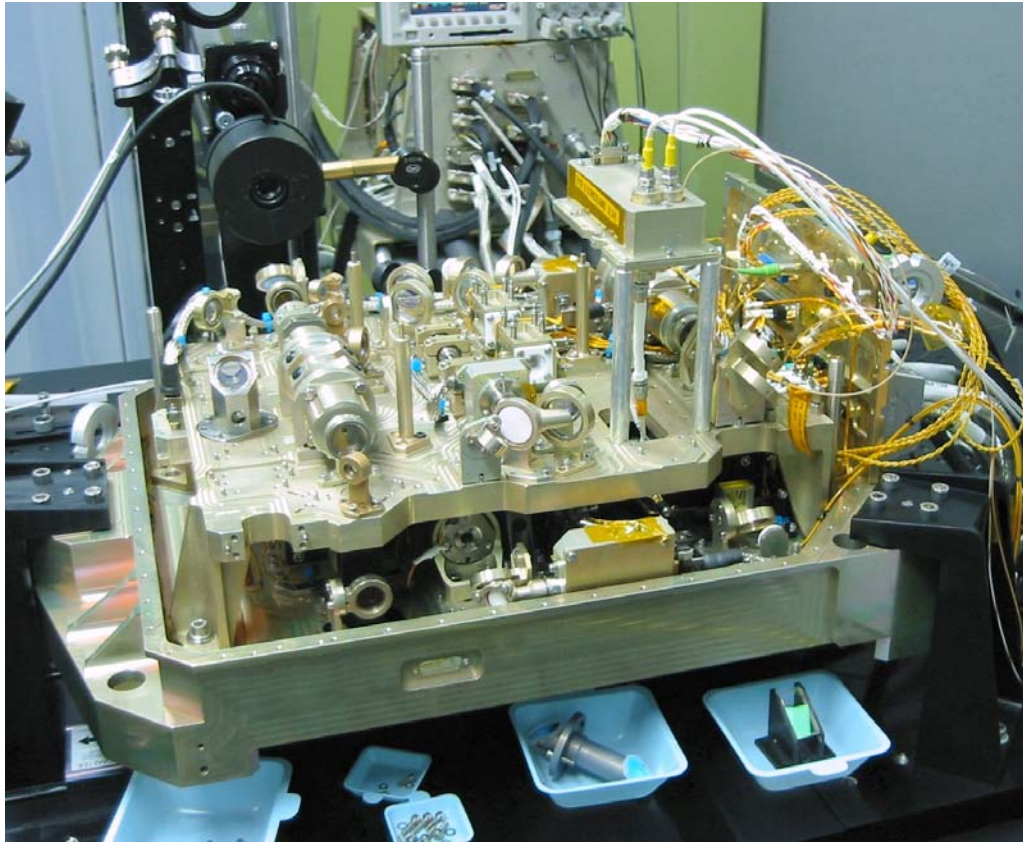
A large radiator (mounted on the satellite bus) is coupled with heat pipes to the transmitter lasers.

Star trackers are mounted on ALADIN structure to give best possible pointing reference.

Total mass is 470 kg, 830 W power need (average).



## **ALADIN transmitter laser (TXA)**



A diode pumped Nd:YAG laser is generating single frequency pulses at 355 nm wavelength with 150 mJ energy at 100 Hz repetition rate.

It is operated in burst mode of 12 s on (5 s warm up, 7 s measurement), and 16 s off to increase life time and reduce power consumption.

For single mode operation, the laser is injection seeded with output from a cw MISER laser in the Reference Laser Head (RLH) which is coupled via single-mode fibres to the power laser head.

The laser is conductively cooled via heat pipes mounted on thermal interface plates.

# ...and the complete Aeolus satellite

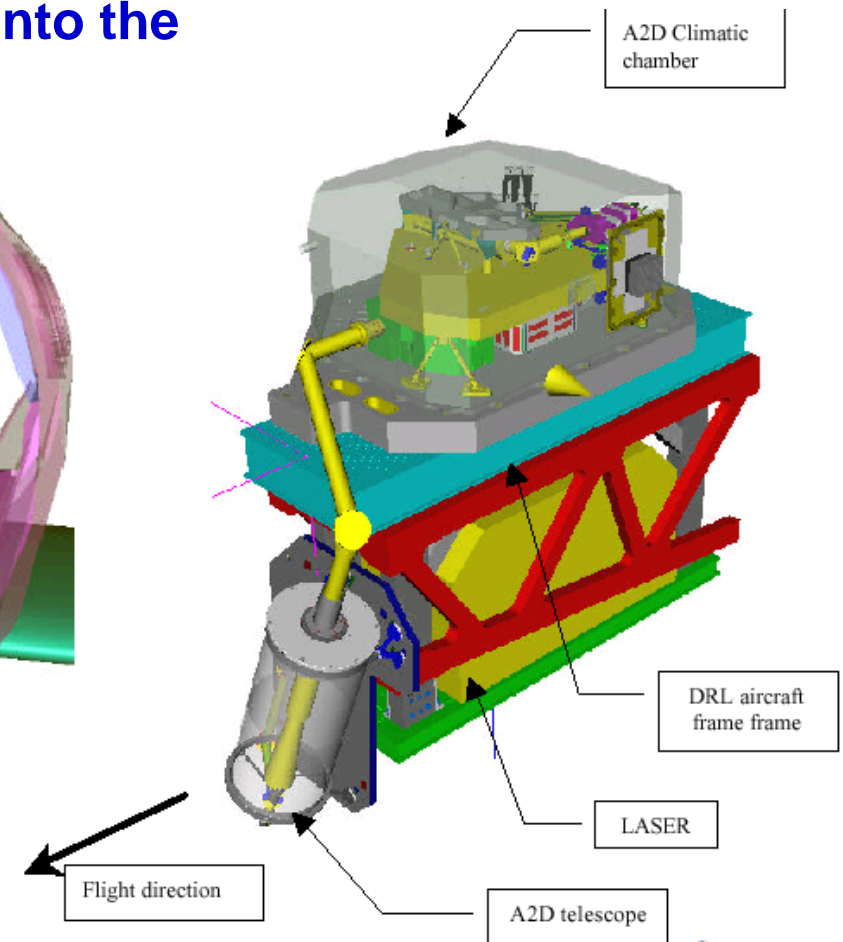
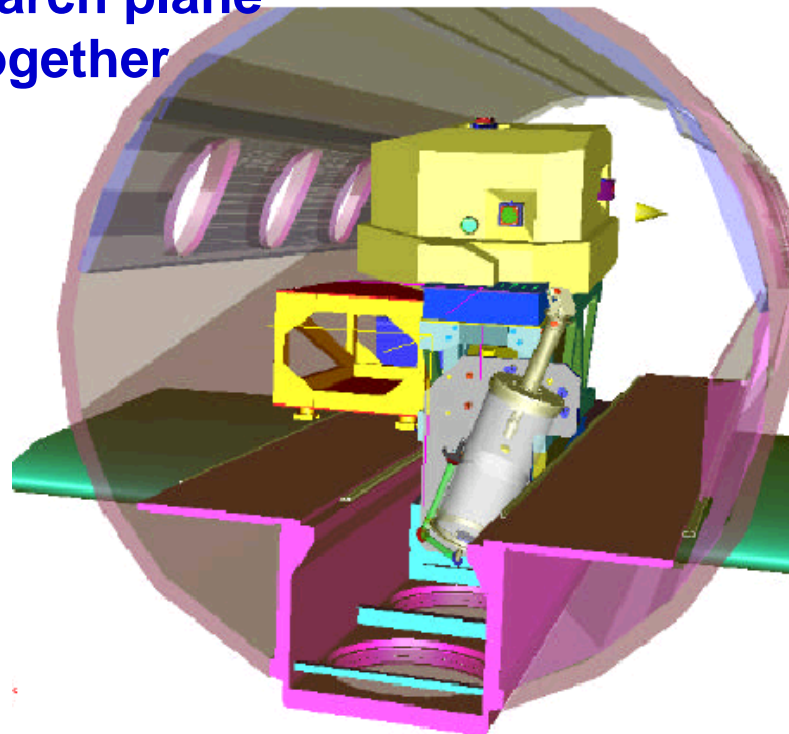


**Aeolus  
Structure  
Model in  
ESTEC,  
June 2005**

# ALADIN Airborne Demonstrator A2D



The pre-development model of the receiver and one of the breadboard lasers have been combined to a complete wind lidar to fit into the Falcon research plane from DLR together with the CTI 2-um wind lidar

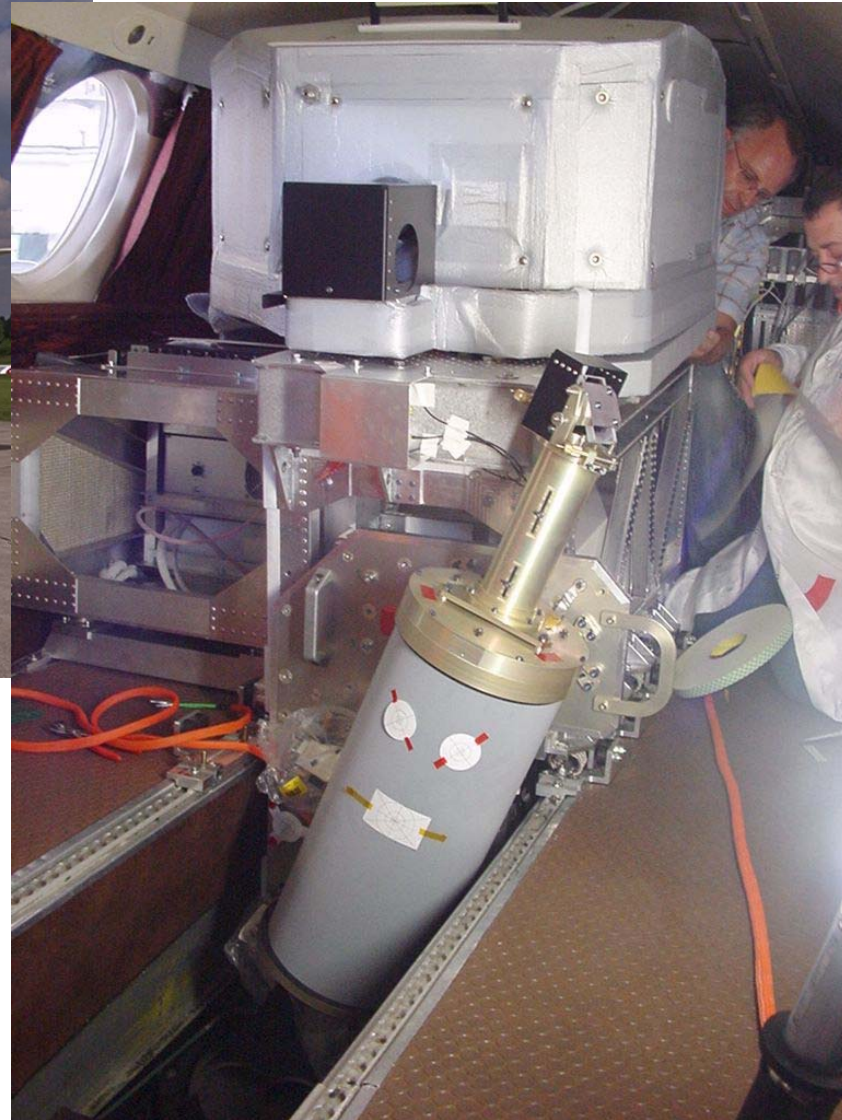


## ...and the A2D in D-CMET



### DLR Falcon 20 aircraft

- pressurized cabin
- max. altitude 13 km
- cruising time 4 h



**A2D during acceptance testing  
after installation in D-CMET on  
for first proof flight 18 Oct 2005**

## Aeolus will be first spaceborne wind lidar



First space mission to  
measure global wind  
profiles

Mie and Rayleigh receivers  
allow to measure wind  
profiles up to 30 km

Aeolus should evolve into  
operational wind profilers  
a series of dedicated  
wind satellite in dusk-  
dawn orbit would fulfill  
the demands on global  
data coverage

All systems are in  
manufacturing phase